Some properties for superprocess under a stochastic flow

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Abstract

For a superprocess under a stochastic flow, we prove that it has a density with respect to the Lebesgue measure for d=1 and is singular for d>1. For d=1, a stochastic partial differential equation is derived for the density. The regularity of the solution is then proved by using Krylov's L_p -theory for linear SPDE. A snake representation for this superprocess is established. As applications of this representation, we prove the compact support property for general d and singularity of the process when d>1.

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1 Introduction

Superprocesses under stochastic flows have been studied by many authors since the work of Wang ([11],[12]) and Skoulakis and Adler [9]. At an early stage, this problem was studied as the high-density limit of a branching particle system while the motion of

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each particle is governed by an independent Brownian motion as well as by a common Brownian motion which determines the stochastic flow. The limit is characterized by a martingale problem whose uniqueness is established by a moment duality. Before we go any further, let us introduce the model in more detail.

Let $b: \mathbb{R}^d \to \mathbb{R}^d$, σ_1 , $\sigma_2: \mathbb{R}^d \to \mathbb{R}^{d \times d}$ be measurable functions. Let W, B_1 , B_2 , \cdots be independent d-dimensional Brownian motions. Consider a branching particle system performing independent binary branching. Between branching times, the motion of the ith particle is governed by the following stochastic differential equation (SDE):

$$d\eta_i(t) = b(\eta_i(t))dt + \sigma_1(\eta_i(t))dW(t) + \sigma_2(\eta_i(t))dB_i(t). \tag{1.1}$$

It is proved by Skoulakis and Adler [9] that the high-density limit X_t is the unique solution to the following martingale problem (MP): $X_0 = \mu \in \mathcal{M}_F(\mathbb{R}^d)$, where $\mathcal{M}_F(\mathbb{R}^d)$ denotes the space of finite nonnegative measures on \mathbb{R}^d and for any $\phi \in C_0^2(\mathbb{R}^d)$,

$$M_t(\phi) \equiv \langle X_t, \phi \rangle - \langle \mu, \phi \rangle - \int_0^t \langle X_s, L\phi \rangle \, ds \tag{1.2}$$

is a continuous martingale with quadratic variation process

$$\langle M(\phi) \rangle_t = \int_0^t \left(\langle X_s, \phi^2 \rangle + \left| \langle X_s, \sigma_1^T \nabla \phi \rangle \right|^2 \right) ds$$
 (1.3)

where

$$L\phi = \sum_{i=1}^{d} b^{i} \partial_{i} \phi + \frac{1}{2} \sum_{i,j=1}^{d} a^{ij} \partial_{ij}^{2} \phi,$$

 $a^{ij} = \sum_{k=1}^{d} \sum_{\ell=1}^{2} \sigma_{\ell}^{ik} \sigma_{\ell}^{kj}$, ∂_{i} means the partial derivative with respect to the *i*th component of $x \in \mathbb{R}^{d}$, σ_{1}^{T} is the transpose of the matrix σ_{1} , $\nabla = (\partial_{1}, \dots, \partial_{d})^{T}$ is the gradient operator and $\langle \mu, f \rangle$ represents the integral of the function f with respect to the measure μ . It was conjectured in [9] that the conditional log-Laplace transform of X_{t} should be the unique solution to a nonlinear stochastic partial differential equation (SPDE). Namely

$$\mathbb{E}_{\mu}\left(e^{-\langle X_t, f\rangle} \middle| W\right) = e^{-\langle \mu, y_{0,t}\rangle} \tag{1.4}$$

and

$$y_{s,t}(x) = f(x) + \int_{s}^{t} (Ly_{r,t}(x) - y_{r,t}(x)^{2}) dr + \int_{s}^{t} \nabla^{T} y_{r,t}(x) \sigma_{1}(x) dW(r)$$
(1.5)

where $\hat{d}W(r)$ represents the backward Itô integral:

$$\int_{s}^{t} g(r)\hat{d}W(r) = \lim_{|\Delta| \to 0} \sum_{i=1}^{n} g(r_{i}) (W(r_{i}) - W(r_{i-1}))$$

where $\Delta = \{r_0, r_1, \dots, r_n\}$ is a partition of [s, t] and $|\Delta|$ is the maximum length of the subintervals.

This conjecture was confirmed by Xiong [13] under the following conditions (BC) which will be assumed throughout this paper: $f \geq 0$, b, σ_1 , σ_2 are bounded with bounded first and second derivatives. $\sigma_2^T \sigma_2$ is uniformly positive definite, σ_1 has third continuous bounded derivatives. f is of compact support.

Making use of the conditional log-Laplace functional, the long-term behavior of this process is studied in [14]. Also, the model has been extended in that paper to allow infinite measures $\mu \in \mathcal{M}_{tem}(\mathbb{R}^d)$, namely, $\int_{\mathbb{R}^d} e^{-\lambda |x|} \mu(dx) < \infty$ for some $\lambda > 0$. We shall assume $\mu \in \mathcal{M}_{tem}(\mathbb{R}^d)$ throughout this paper. A similar model has been investigated by Wang [12] and Dawson et al [1] when the spatial dimension is 1. Further, in that case, it is proved by Dawson et al [2] that their process is density-valued and solves a SPDE. The regularity of the solution was left *open* in that article.

This paper is organized as follows: In Section 2, we establish a snake representation for X_t . As immediate consequences to this representation, we get the compact support property of X_t (for all d) and for d > 1, X_t takes values in the set of singular measures. Then, for d = 1, we prove in Section 3 that X_t is absolutely continuous with respect to Lebesgue measure and show that the density X(t, x) satisfies the following SPDE

$$\partial_t X = L^* X - \partial_x (\sigma_1 X) \dot{W}_t + \sqrt{X} \dot{B}_{tx}$$
 (1.6)

where B is a Brownian sheet and L^* is the adjoint operator of L. The main result of this paper is to show the Hölder continuity of X(t,x).

Here is the main result. First recall that for $n \in \mathbb{R}$ and $p \in [2, \infty)$, H_p^n is the space of Bessel potentials with norm

$$||u||_{n,p} = ||(I - \Delta)^{n/2}u||_p.$$

Theorem 1.1 Suppose that Condition (BC) is satisfied. Then

- i) If d > 1, then X_t is singular a.s.
- ii) If d = 1, then X_t is absolutely continuous with respect to Lebesgue measure and the density satisfies the SPDE (1.6).
- iii) If in addition, μ satisfies $\mu \in H_p^{\frac{1}{2}-\epsilon-2/p}$ with $\epsilon \in (0,\frac{1}{4})$ and $p > \frac{1}{\epsilon}$ and also satisfies

$$\sup_{t,x} \langle \mu, \varphi_t(x - \cdot) \rangle < \infty, \tag{1.7}$$

then the density X(t,x) is Hölder continuous in x with index $\frac{1}{2} - 2\epsilon$ for (a.e.) t a.s., where $\varphi_t(x)$ is the density of a normal random variable with mean 0 and variance t.

Note that (1.7) is satisfied if μ has bounded density with respect to Lebesgue measure.

Suppose that we apply the usual integral equation as in [10], Chapter 3, for (1.6) in order to prove the Hölder continuity. Then formally we have

$$X(t,x) = \int p_0(t,x,y)X(0,y)dy + \int_0^t \int \sigma_1(y)X(s,y)\partial_y p_0(t-s,x,y)dydW(s)$$
$$+ \int_0^t \int \sqrt{X(s,y)}p_0(t-s,x,y)B(dsdy)$$

where p_0 is the transition function of the Markov process with generator L. However, the second term on the right hand side of the above equation is about

$$\int_0^t (t-s)^{-1/2} dW(s)$$

which is *not* convergent. Therefore, the convolution argument used by Konno and Shiga [5] does not apply to our model. In Section 4, we freeze the nonlinear term in (1.6) and apply Krylov's L_p -theory for linear SPDE to get the Hölder continuity with index slightly less than $\frac{1}{2}$ for X.

Note that the SPDE in [2] is (1.6) in current paper with \dot{W}_t replaced by a spacetime noise which is colored in space and white in time. The method of this paper can be applied to that equation to prove the regularity for its solution.

2 Snake representation

In this section, we construct a path-valued process \mathcal{Y}_t such that the process X_t can be represented according to this process. Then, as an easy application of this representation, we derive the properties for X_t .

For the convenience of the reader, we recall some basic definitions and facts taken from Le Gall [8]. Let $\zeta \geq 0$ and let f be a continuous function from \mathbb{R}_+ to \mathbb{R}^d such that $f(s) = f(\zeta)$, $\forall s \geq \zeta$. We call such pair (f, ζ) a stopped path with ζ being the lifetime of the path. We denote the collection of all stopped paths by \mathbb{W} . For (f, ζ) , $(f', \zeta') \in \mathbb{W}$, define a distance

$$\delta((f,\zeta),(f',\zeta')) = \sup_{s \ge 0} |f(s) - f'(s)| + |\zeta - \zeta'|.$$

Then (\mathbb{W}, δ) is a Polish space. In [8], Le Gall constructed a continuous time-homogeneous strong Markov process (\mathcal{Z}_t, ζ_t) taking values on \mathbb{W} . ζ_t is a one-dimensional reflecting Brownian motion. Given ζ , the process \mathcal{Z} has the following property: for all r < t, and for all $s \leq m_{r,t} := \inf_{r \leq u \leq t} \zeta_u$ we have $\mathcal{Z}_r(s) = \mathcal{Z}_t(s)$. Furthermore, given $m_{r,t}$ and $\mathcal{Z}_r(m_{r,t})$, the processes $\mathcal{Z}_r(s) : s \geq m_{r,t}$ and $\mathcal{Z}_t(s) : s \geq m_{r,t}$ are conditionally independent Brownian motions with lifetimes ζ_r and ζ_t respectively.

Denote the strong solution to the SDE

$$d\eta(t) = b(\eta(t))dt + \sigma_1(\eta(t))dW(t) + \sigma_2(\eta(t))dB(t)$$

by $\eta(t) = F(t, W, B)$. Define the following path-valued process

$$\mathcal{Y}_t(s) = F(s, W, \mathcal{Z}_t)$$

with the life-time process ζ_t .

Lemma 2.1 (\mathcal{Y}_t, ζ_t) is a continuous \mathbb{W} -valued process.

Proof: Note that for all r < t and for all $s < m_{r,t}$, we have $\mathcal{Y}_r(s) = \mathcal{Y}_t(s)$. Furthermore, for given $\mathcal{Y}_r(m_{r,t})$, the processes $\mathcal{Y}_r(s) : s \ge m_{r,t}$ and $\mathcal{Y}_t(s) : s \ge m_{r,t}$ are the motions of two particles (say, η_1 and η_2) given as in the introduction with lifetimes ζ_r and ζ_t starting from the same position $\mathcal{Y}_r(m_{r,t})$. A simple application of Burkholder's inequality gives

$$\mathbb{E}\left[\sup_{m \le s \le M} |\eta_1(s) - \eta_2(s)|^k\right] \le K|M - m|^{k/2},$$

where $m = m_{r,t}$ and $M = \zeta_r \vee \zeta_t$. Denote by \mathbb{E}^{ζ} the conditional expectation given ζ . Then

$$\mathbb{E}\left[\sup_{s\geq 0}|\mathcal{Y}_{r}(s)-\mathcal{Y}_{t}(s)|^{k}\right] = \mathbb{E}\left[\mathbb{E}^{\zeta}\left\{\sup_{s\geq m_{r,t}}|\mathcal{Y}_{r}(s)-\mathcal{Y}_{t}(s)|^{k}\right\}\right]$$

$$\leq \mathbb{E}\left[K|\zeta_{r}+\zeta_{t}-2m_{r,t}|^{k/2}\right]$$

$$\leq K\mathbb{E}\left[\sup_{s\in[r,t]}|\zeta_{s}-\zeta_{r}|^{k/2}\right]$$

$$\leq K|t-r|^{k/4}.$$

The conclusion follows from Kolmogorov's criteria by taking k > 4; see [10] for Kolmogorov's criteria.

Theorem 2.2

$$X_t(f) = \int_t^{\tau} f(\mathcal{Y}_s(\zeta_s)) d\ell_s^t$$
 (2.1)

where ℓ^t is the local time process of ζ at level t and

$$\tau = \inf\{s: \ \ell_s^0 \ge 1\}.$$

Proof: Fix a parameter h > 0. For every $t \ge 0$, denote by $[a_t^1, b_t^1], [a_t^2, b_t^2], \dots, [a_t^{N_t}, b_t^{N_t}]$ the excursion intervals of $(\zeta_s)_{0 \le s \le \tau}$ above level t, corresponding to excursions of height greater than h. Set

$$X_t^h = 2h \sum_{i=1}^{N_t} \delta_{\mathcal{Y}_{a_t^i}(t)}.$$

Then X_t^h is the measure-valued process corresponding to the branching particle system described as follows: At time t=0, we have N_0 particles in \mathbb{R}^d with Poisson random measure with intensity measure $h^{-1}\mu$. The particles then move according to (1.1) with common W and independent B_i 's. Each of them has a finite lifetime (independent of others) which is exponential with mean h. When a particle dies, it gives rise to either 0 or 2 new particles with probability $\frac{1}{2}$. The new particles start from the position of the their father. As in the proof of Theorem 2.1 in [8], by the well-known approximation of Brownian local time by upcrossing numbers, we have that X_t^h converges weakly to X_t , where X_t is given by the right hand side of (2.1).

As an application of the snake representation, we have the following immediate consequence.

Corollary 2.3 If μ is a finite measure, then for any t > 0, X_t has compact support a.s.

Proof: By the snake representation, there exists a finite set I such that

$$\langle X_t, f \rangle = \sum_{i \in I} \int_0^{\tau_i} f(\hat{\mathcal{Y}}_s^i) d\ell_s^t(\zeta^i)$$

where $\hat{\mathcal{Y}}_s^i$ is the tip of the *i*th snake. It is not hard to show that $\hat{\mathcal{Y}}_s^i$ is continuous and hence, for any $t_0 > 0$,

$$\bigcup_{t > t_0} \operatorname{supp}(X_t) \subset \overline{\bigcup_{i \in I} \operatorname{Range}\left(\hat{\mathcal{Y}}^i\right)} = \bigcup_{i \in I} \{\hat{\mathcal{Y}}^i_s : 0 \le s \le \tau_i\}$$
(2.2)

is compact.

To consider the case for μ being σ -finite, the following conditional martingale problem (CMP) is useful. The following lemma was proved in [14].

Lemma 2.4 i) If X_t is the solution to MP, then there exists a Brownian motion W_t such that for any $\phi \in C_0^2(\mathbb{R}^d)$,

$$N_t(\phi) \equiv \langle X_t, \phi \rangle - \langle \mu, \phi \rangle - \int_0^t \langle X_s, L\phi \rangle \, ds - \int_0^t \langle X_s, \sigma_1^T \nabla \phi \rangle \, dW_s \tag{2.3}$$

is a continuous $(\mathbb{P}, \mathcal{G}_t)$ -martingale with quadratic variation process

$$\langle N(\phi)\rangle_t = \int_0^t \langle X_s, \phi^2 \rangle ds$$
 (2.4)

where $\mathcal{G}_t = \mathcal{F}_t \vee \mathcal{F}_{\infty}^W$.

ii) If X_t is a solution to CMP, then it is a solution to MP.

As another application of the snake representation, we have

Corollary 2.5 If $d \ge 2$, then X_t is singular.

Proof: If μ is finite and d > 1, it follows from (2.2) the support is of Lebesgue measure 0 since $\{\hat{\mathcal{Y}}_s^i: 0 \leq s \leq \tau_i\}$ is a continuous (one-dimensional) curve in \mathbb{R}^d . If μ is σ -finite, we can take $\mu = \sum_{n=1}^{\infty} \mu^n$ with μ^n finite. Construct the solution X_t^n to CMP with the same W and with initial μ^n , $n = 1, 2, \cdots$. Then

$$X_t = \sum_{n=1}^{\infty} X_t^n$$

is the solution to CMP with initial μ . Then $\operatorname{supp}(X_t^n)$ has Lebesgue measure 0 and hence, so does the support of X_t . This implies that X_t is a singular measure a.s.

3 SPDE for d=1

In this section, we prove that X_t has a density which satisfies the SPDE (1.6) whose mild form is

$$\langle X_t, f \rangle = \langle \mu, f \rangle + \int_0^t \langle X_s, Lf \rangle \, ds + \int_0^t \langle X_s, \sigma_1 f' \rangle \, dW_r$$
$$+ \int_0^t \int_{\mathbb{R}} \sqrt{X_s(x)} f(x) B(ds dx). \tag{3.1}$$

Let $p_0(t, x, y)$ and $q_0(t, (x_1, x_2), (y_1, y_2))$ be the transition density functions of the Markov processes $\eta_1(t)$ and $(\eta_1(t), \eta_2(t))$ respectively. By Theorem 1.5 of [13], we have

$$\mathbb{E}\left[\langle X_t, f \rangle\right] = \int_{\mathbb{R}^2} f(y) p_0(t, x, y) dy \mu(dx)$$
 (3.2)

and

$$\mathbb{E}\left[\left\langle X_{t}, f\right\rangle \left\langle X_{t}, g\right\rangle\right]
= \int_{\mathbb{R}^{4}} f(y_{1})g(y_{2})q_{0}(t, (x_{1}, x_{2}), (y_{1}, y_{2}))dy_{1}dy_{2}\mu(dx_{1})\mu(dx_{2})
+2 \int_{0}^{t} ds \int_{\mathbb{R}^{4}} p_{0}(t-s, z, y)f(z_{1})g(z_{2})q_{0}(s, (y, y), (z_{1}, z_{2}))dz_{1}dz_{2}dy\mu(dz).$$
(3.3)

Theorem 3.1 If $\mu(\mathbb{R}) < \infty$, then $X_t \in H_0 \equiv L^2(\mathbb{R})$ a.s.

Proof: Take $f = p_0(\epsilon, x, \cdot)$ and $g = p_0(\epsilon', x, \cdot)$ in (3.3). Note that as $\epsilon, \epsilon' \to 0$,

$$\int_{\mathbb{R}^2} p_0(\epsilon, x, z_1) p_0(\epsilon', x, z_2) p_0(t - s, z, y) q_0(t, (y, y), (z_1, z_2)) dz_1 dz_2$$

$$\to p_0(t - s, z, y) q_0(t, (y, y), (x, x)).$$

Note that by Theorem 6.4.5 in Friedman [3], we have

$$p_0(\epsilon, x, y) \le c\varphi_{c'\epsilon}(x - y),$$

$$q_0(s, (y, y), (z_1, z_2)) \le c\varphi_{c's}(y - z_1)\varphi_{c's}(y - z_2)$$

where $\varphi_t(x)$ is the normal density with mean 0 and variance t (introduced earlier). Note that c' is a constant which is usually greater than 1. Since it does not play an essential role, to simplify the notations, we assume c' = 1 throughput the rest of this paper. Hence,

$$\int_{\mathbb{R}^2} p_0(\epsilon, x, z_1) p_0(\epsilon', x, z_2) p_0(t - s, z, y) q_0(s, (y, y), (z_1, z_2)) dz_1 dz_2$$

$$\leq c \int_{\mathbb{R}^2} \varphi_{\epsilon}(x - z_1) \varphi_{\epsilon'}(x - z_2) \varphi_{t-s}(z - y) \varphi_s(y - z_1) \varphi_s(y - z_2) dz_1 dz_2$$

$$= c \varphi_{s+\epsilon}(x - y) \varphi_{s+\epsilon'}(x - y) \varphi_{t-s}(z - y).$$

As

$$\lim_{\epsilon,\epsilon'\to 0} \int_0^T dt \int dx \int_0^t ds \int_{\mathbb{R}^2} \varphi_{s+\epsilon}(x-y) \varphi_{s+\epsilon'}(x-y) \varphi_{t-s}(z-y) dy \mu(dz)$$

$$= \lim_{\epsilon,\epsilon'\to 0} \int_0^T dt \int_0^t ds \varphi_{2s+\epsilon+\epsilon'}(0) \mu(\mathbb{R})$$

$$= \int_0^T dt \int_0^t ds \varphi_{2s}(0) \mu(\mathbb{R})$$

$$= \int_0^T dt \int dx \int_0^t ds \int_{\mathbb{R}^2} \varphi_{t-s}(z-y) \varphi_s(x-y) \varphi_s(x-y) dy \mu(dz),$$

by the dominated convergence theorem, we see that as $\epsilon, \epsilon' \to 0$,

$$\int_{0}^{T} dt \int dx \int_{0}^{t} ds \int_{\mathbb{R}^{4}} p_{0}(t-s,z,y) p_{0}(\epsilon,x,z_{1}) p_{0}(\epsilon',x,z_{2}) q_{0}(s,(y,y),(z_{1},z_{2})) dz_{1} dz_{2} dy \mu(dz)$$

$$\rightarrow \int_{0}^{T} dt \int dx \int_{0}^{t} ds \int_{\mathbb{R}^{2}} p_{0}(t-s,z,y) q_{0}(t,(y,y),(x,x)) dy \mu(dz).$$

Similarly, we have

$$\int_{0}^{T} dt \int dx \int_{\mathbb{R}^{4}} p_{0}(\epsilon, x, y_{1}) p_{0}(\epsilon', x, y_{2}) q_{0}(t, (x_{1}, x_{2}), (y_{1}, y_{2})) dy_{1} dy_{2} \mu(dx_{1}) \mu(dx_{2})$$

$$\rightarrow \int_{0}^{T} dt \int dx \int_{\mathbb{R}^{2}} q_{0}(t, (x_{1}, x_{2}), (x, x)) \mu(dx_{1}) \mu(dx_{2}).$$

Hence

$$\int_{0}^{T} dt \int dx \mathbb{E} \left(\langle X_{t}, p(\epsilon, x, \cdot) \langle X_{t}, p(\epsilon', x, \cdot) \rangle \right)$$

$$\to \int_0^T dt \int dx \int_{\mathbb{R}^2} q_0(t, (x_1, x_2), (x, x)) \mu(dx_1) \mu(dx_2)$$

$$+ \int_0^T dt \int dx \int_0^t ds \int_{\mathbb{R}^2} p_0(t - s, x, y) q_0(t, (y, y), (x, x)) dy \mu(dx).$$

From this, we can show that $\{\langle X_t, p_0(\epsilon, x, \cdot) \rangle : \epsilon > 0\}$ is a Cauchy sequence in $L^2(\Omega \times [0, T] \times \mathbb{R})$. This implies the existence of the density $X_t(x)$ of X_t in $L^2(\Omega \times [0, T] \times \mathbb{R})$.

Next theorem considers infinite measure.

Theorem 3.2 If $\mu \in \mathcal{M}_{tem}(\mathbb{R}^d)$, then X_t has a density $X_t(x)$.

Proof: If μ is σ -finite, we can construct X^n with $X_0^n = \mu^n$ being finite as those in the proof of Corollary 2.5. Then

$$X_t = \sum_{n=1}^{\infty} X_t^n$$

is the solution to CMP with initial μ . Let

$$X_{t}(x) = \sum_{n=1}^{\infty} X_{t}^{n}(x).$$
 (3.4)

By (3.2), we have

$$\mathbb{E} X_t^n(x) = \int_{\mathbb{R}} p_0(t, y, x) \mu^n(dy).$$

As

$$p_0(t, x, y) \le c\varphi_t(x - y) \le c(t, \lambda, x)e^{-\lambda|y|},$$

for any $\lambda > 0$, we have

$$\mathbb{E} \sum_{n=1}^{\infty} X_t^n(x) = \sum_{n=1}^{\infty} \int_{\mathbb{R}} p_0(t, y, x) \mu^n(dy)$$
$$= \int_{\mathbb{R}} p_0(t, y, x) \mu(dy) < \infty.$$

Hence, $X_t(x)$ is well-defined by (3.4). It is then easy to show that $X_t(x)dx = X_t(dx)$.

Finally, we derive the SPDE satisfied by the density.

Theorem 3.3 If d = 1, then X_t is the (weak) unique solution to the SPDE (3.1).

Proof: Note that $N_t(\phi)$ is a continuous $(\mathbb{P}, \mathcal{G}_t)$ -martingale with quadratic variation process

$$\langle N(\phi) \rangle_t = \int_0^t \int_{\mathbb{R}} \left(\sqrt{X_s(x)} \phi(x) \right)^2 dx ds.$$

By the martingale representation theorem ([4], Theorem 3.3.5), there exists an $L^2(\mathbb{R})$ cylindrical Brownian motion \tilde{B} on an extension of $(\Omega, \mathcal{F}, \mathcal{G}_t, \mathbb{P})$ such that

$$N_t = \int_0^t \left\langle \sqrt{X_s}, d\tilde{B}_s \right\rangle_{L^2(\mathbb{R})}.$$

There exists a standard Brownian sheet B such that

$$\tilde{B}_t(h) = \int_0^t \int_{\mathbb{R}} h(x)B(dsdx), \quad \forall h \in L^2(\mathbb{R}).$$

Therefore,

$$N_t(\phi) = \int_0^t \int_{\mathbb{R}} \sqrt{X_s(x)} \phi(x) B(dsdx).$$

As B is a Brownian sheet on an extension of \mathcal{G}_t , it is easy to show that B is independent of W.

4 Hölder Continuity

This section is devoted to the proof of the main result: Theorem 1.1 (iii). Namely, in this section, we consider the regularity of the solution to the nonlinear SPDE (1.6). We use the linearization and Krylov's L_p -theory for linear SPDE.

We will paraphrase the condition (BC) to find some reasonable assumptions for σ_1, σ_2, b to make our regularity argument easy. Note that these functions are scalar functions since we are dealing with the situation d = 1. Therefore, we have $L = \frac{1}{2}a\partial_{xx} + b\partial_x$ and $L^* = \frac{1}{2}a\partial_{xx} + (a' - b)\partial_x + (\frac{1}{2}a'' - b')$.

We start by defining some basic spaces. We denote

$$[f]_0 = \sup_{x \in \mathbb{R}} |f(x)|, \quad [f]_\gamma = \sup_{x \neq y} \frac{|f(x) - f(y)|}{|x - y|^\gamma}$$

for $\gamma \in (0,1]$. Using this notation, we define

$$||f||_{C^{0,\gamma}} = [f]_0 + [f]_{\gamma}, \quad ||f||_{C^{1,\gamma}} = [f]_0 + [f']_0 + [f']_{\gamma}$$
$$||f||_{C^1} = [f]_0 + [f']_0, \quad ||f||_{C^2} = [f]_0 + [f']_0 + [f'']_0$$

assuming that f' or f'' exist if they appear in the corresponding definition. Then we define the Banach spaces :

$$C^{0,\gamma} = \{ f : ||f||_{C^{0,\gamma}} < \infty \}, \quad C^{1,\gamma} = \{ f : ||f||_{C^{1,\gamma}} < \infty \}$$
$$C^1 = \{ f : ||f||_{C^1} < \infty \}, \quad C^2 = \{ f : ||f||_{C^2} < \infty \}.$$

Remark 4.1 Zygmund spaces $C^{0,\gamma}$, $C^{1,\gamma}$ are the usual Hölder spaces if $\gamma \in (0,1)$. It is easy to see that we have $||f||_{C^{0,\gamma}} \leq 2||f||_{C^{0,1}}$, $||f||_{C^{1,\gamma}} \leq 2||f||_{C^{1,1}}$ and $||f||_{C^{0,1}} \leq ||f||_{C^{1,1}} \leq ||f||_{C^{1,1}} \leq ||f||_{C^{2}}$ when f' or f'' exists.

Now, we state assumptions on σ_1, σ_2, b . First, our condition (BC) gives us the following assumption:

$$\sigma_1, \sigma_2 \in C^2, \quad b \in C^1 \tag{4.1}$$

which, in particular, implies $a = \sigma_1^2 + \sigma_2^2 \in C^2$. We also assume that

$$\delta \le \frac{1}{2}a, \frac{1}{2}\sigma_2^2 \le K, \quad \|\sigma_1\|_{C^2}, \|\sigma_2\|_{C^2}, \|b\|_{C^1} \le K$$

$$(4.2)$$

for some positive constants δ, K .

Next, we recall the basic definitions of some function spaces defined in [7]. In addition to the definition about space of Bessel potentials in the Theorem 1.1, we also

define the following: for $n \in \mathbb{R}$ and $p \in [2, \infty)$ let $H_p^n(l_2)$ be the space with norm

$$||g||_{n,p} = |||(I - \Delta)^{n/2}g|_{l_2}||_{p}$$

for l_2 -valued functions $g = \{g^k\}$. Then we define

$$\mathbb{H}_p^n(T) = L_p(\Omega \times [0,T], \mathcal{P}, H_p^n) \quad \mathbb{H}_p^n(T, l_2) = L_p(\Omega \times [0,T], \mathcal{P}, H_p^n(l_2))$$

where \mathcal{P} is the predictable σ -field. We denote $\mathbb{L}_p(T) = \mathbb{H}_p^0(T)$. Let $\{w_t^k : k = 1, 2, \ldots\}$ be a family of independent one-dimensional Brownian motions.

We say $u \in \mathcal{H}_p^n(T)$ if $\partial_{xx}u \in \mathbb{H}_p^{n-2}(T)$ and $u(0,\cdot) \in L_p(\Omega, H_p^{n-2/p})$ and there exists $(f,g) \in \mathbb{H}_p^{n-2}(T) \times \mathbb{H}_p^{n-1}(T,l_2)$ such that $\forall \phi \in C_0^{\infty}(\mathbb{R})$, (a.s.)

$$\langle u_t, \phi \rangle = \langle u_0, \phi \rangle + \int_0^t \langle f_s, \phi \rangle \, ds + \sum_{k=0}^\infty \int_0^t \langle g_s^k, \phi \rangle \, dw_s^k$$

holds for all $t \leq T$. We denote

$$||u||_{\mathcal{H}_{p}^{n}(T)} = ||\partial_{xx}u||_{\mathbb{H}_{p}^{n-2}(T)} + ||f||_{\mathbb{H}_{p}^{n-2}(T)} + ||g||_{\mathbb{H}_{p}^{n-1}(T,l_{2})} + \left(\mathbb{E} ||u_{0}||_{n-2/p,p}^{p}\right)^{1/p}$$

Reader can find motivation of this definition and detailed remarks in [7].

Now, we fix $\epsilon \in (0, \frac{1}{4})$ and proceed to the *Proof of Theorem 1.1 (iii)*: First, we freeze the nonlinear term of SPDE (1.6) and consider the following auxiliary linear SPDE for $Y_t(x)$:

$$\begin{cases} \partial_t Y = L^* Y + \sqrt{X} \dot{B}_{tx} \\ Y_0 = \mu \end{cases}$$
 (4.3)

where we assume $\mu \in H_p^{\frac{1}{2} - \epsilon - 2/p}$.

Then Z = X - Y satisfies

$$\begin{cases}
\partial_t Z = L^* Z - (\partial_x (\sigma_1 Z) + \partial_x (\sigma_1 Y)) \dot{W}_t \\
Z_0 = 0.
\end{cases}$$
(4.4)

We apply Theorem 8.5 of [7] to (4.3). To do this we need the coefficients of L^* and \sqrt{X} to satisfy

$$||a||_{C^{1,1}} < \infty, \quad ||a' - b||_{C^{0,1}} < \infty, \quad [\frac{1}{2}a'' - b']_0 < \infty, \quad ||\sqrt{X}||_{\mathbb{L}_p(T)} < \infty.$$

In fact, we have

$$||a||_{C^{1,1}} \le K$$
, $||a' - b||_{C^{0,1}} \le 2K$, $[\frac{1}{2}a'' - b']_0 \le 2K$

by our assumptions (4.1) and (4.2) and Remark 4.1. We will prove $\|\sqrt{X}\|_{\mathbb{L}_p(T)} < \infty$ later and take this for granted in this proof.

Now, by Theorem 8.5 of [7] to (4.3) and the first assertion of Lemma 8.4 and the fact that μ is nonrandom, we have a unique solution Y in $\mathcal{H}_p^{\frac{1}{2}-\epsilon}(T)$ with estimate

$$||Y||_{\mathcal{H}_{p}^{\frac{1}{2}-\epsilon}(T)} \le N(||\sqrt{X}||_{\mathbb{L}_{p}(T)} + ||\mu||_{\frac{1}{2}-\epsilon-2/p,p})$$
 (4.5)

where N depends only on $\epsilon, p, \delta, K, T$.

Now we use Theorem 5.1 in [7] for equation (4.4) above with $n = -\frac{3}{2} - \epsilon \in (-2, -\frac{3}{2})$. Note $\partial_x(\sigma_1 Z) = \sigma_1 \partial_x Z + \partial_x \sigma_1 Z$. If we read [7] carefully, we can see that the following conditions are required:

(i)

$$\delta \le \frac{1}{2}a - \frac{1}{2}\sigma_1^2 (= \frac{1}{2}\sigma_2^2) \le K_1$$

for some positive δ, K_1 .

- (ii) a, σ_1 are Lipschitz continuous with Lipschitz constant K_1 .
- (iii) $a \in C^{1,\gamma_1}, \sigma_1 \in C^{0,\gamma_2}$ for some $\gamma_1, \gamma_2 \in (0,1)$ and $||a||_{C^{1,\gamma_1}} + ||\sigma||_{C^{0,\gamma_2}} \le K_1$
- (iv) $||a'-b||_{C^{0,\gamma_3}} + [\frac{1}{2}(a''-b')]_0 + [\partial_x \sigma_1]_0 \le K_1$ for some $\gamma_3 \in (0,1)$.
- (v) $\partial_x(\sigma_1 Y) \in \mathbb{H}_p^{n+1}(T) \ (= \mathbb{H}_p^{-\frac{1}{2}-\epsilon}(T)).$

But, conditions (i) through (iv) are satisfied under (4.1) and (4.2) and Remark 4.1. Note that we can take some constant multiple of K^2 as K_1 . On the other hand, (v) is also satisfied. For

$$\|\partial_x(\sigma_1 Y)\|_{\mathbb{H}_n^{-\frac{1}{2}-\epsilon}(T)} \le N \|\sigma_1 Y\|_{\mathbb{H}_n^{\frac{1}{2}-\epsilon}(T)}$$
 (4.6)

$$\leq N \|\sigma\|_{C^{0,\frac{1}{2}-\epsilon+\frac{1}{4}}} \|Y\|_{\mathbb{H}^{\frac{1}{2}-\epsilon}_{\infty}(T)}$$
 (4.7)

$$\leq N \|\sigma\|_{C^1} \|Y\|_{\mathbb{H}^{\frac{1}{2}-\epsilon}(T)}$$
 (4.8)

$$\leq N \|Y\|_{\mathcal{H}_{2}^{\frac{1}{2}-\epsilon}(T)} \tag{4.9}$$

$$\leq N \|\sqrt{X}\|_{\mathbb{L}_p(T)} + N \|\mu\|_{\frac{1}{2} - \epsilon - 2/p, p} < \infty.$$
 (4.10)

(4.6) follows the observation $\partial_x = \partial_x (I - \Delta)^{-1/2} (I - \Delta)^{1/2}$ and the boundness of the operator $\partial_x (I - \Delta)^{-1/2}$. (4.7) follows Lemma 5.1 (i) in [7]. Up to this step, N only depends on ϵ, p . Note that $\frac{1}{2} - \epsilon + \frac{1}{4}$ is still in (0,1) since $\frac{1}{2} - \epsilon \in (\frac{1}{4}, \frac{1}{2})$. Hence, we have (4.8) by (4.2) and Remark 4.1. (4.9) follows Theorem 3.7 in [7] and N depends only on ϵ, p, K, T now. Finally, (4.5) gives us (4.10) with $N = N(\epsilon, p, \delta, K, T)$.

Therefore, we have a unique solution Z in $\mathcal{H}_p^{\frac{1}{2}-\epsilon}(T)$ with

$$||Z||_{\mathcal{H}_{p}^{\frac{1}{2}-\epsilon}(T)} \le N ||\partial_{x}(\sigma_{1}Y)||_{\mathbb{H}_{p}^{-\frac{1}{2}-\epsilon}(T)} \le N ||\sqrt{X}||_{\mathbb{L}_{p}(T)} + N ||\mu||_{\frac{1}{2}-\epsilon-2/p,p}$$
(4.11)

where $N = N(\epsilon, p, \delta, K, T)$.

Thus, combining (4.5) and (4.11), we have $X = Y + Z \in \mathcal{H}_p^{\frac{1}{2} - \epsilon}(T)$ with estimate

$$||X||_{\mathcal{H}_{p}^{\frac{1}{2}-\epsilon}(T)} \le N||\sqrt{X}||_{\mathbb{L}_{p}(T)} + N||\mu||_{\frac{1}{2}-\epsilon-2/p,p}. \tag{4.12}$$

By the embedding Theorem 7.1 in [7], this implies

$$\left(E\int_0^T \|X_t\|_{C^{\frac{1}{2}-\epsilon-\frac{1}{p}}}^p dt\right)^{1/p} \le N\|X\|_{\mathcal{H}_p^{\frac{1}{2}-\epsilon}(T)} \le N\|\sqrt{X}\|_{\mathbb{L}_p(T)} + N\|\mu\|_{\frac{1}{2}-\epsilon-2/p,p}.$$

So, for large $p > \frac{1}{\epsilon}$, we have

$$||X_t||_{C^{\frac{1}{2}-2\epsilon}} < \infty$$

for (a.e.) $t \in [0, T]$ a.s.. we are done with the proof.

Finally, we use the moment dual to prove that

$$\mathbb{E} \int_0^T \int_{\mathbb{R}} X(t, x)^n dx dt < \infty \tag{4.13}$$

for all $n \in \mathbb{N}$.

Let n_t be a pure-death Markov chain with $n_0 = 0$ and, at a rate $\frac{1}{2}n(n-1)$, jumps from n to n-1. Let $0 = \tau_0 < \tau_1 < \dots < \tau_{n-1}$ be the jump times. Let $f_0 = \delta_x^{\otimes n}$ and for $t < \tau_1$, $f_t(y) = p_0^n(t, (x, \dots, x), y)$, $\forall y \in \mathbb{R}^n$ where p_0^n is the transition function of the n-dimensional diffusion $(\eta_1(t), \dots, \eta_n(t))$. For $f \in C(\mathbb{R}^n)$, let $G_{ij}f \in C(\mathbb{R}^{n-1})$ be given by

$$G_{ij}f(y_1,\dots,y_{n-2},y_{n-1})=f(y_1,\dots,y_{n-1},\dots,y_{n-1},\dots,y_{n-2})$$

where y_{n-1} is at *i*th and *j*th position. Let

$$f_{\tau_1} = \Gamma_1 f_{\tau_1 -}$$

where Γ_1 is a random element taking values in $\{G_{ij}: 1 \leq i < j \leq n\}$ uniformly. We continue this procedure to get the process f_t . Replace f_0 by a smooth function $f_0^k \geq 0$ approximating f_0 . Denote the process constructed above with f_0^k in place of f_0 by f_t^k . Similar to Theorem 11 in Xiong and Zhou [15], we have

$$\mathbb{E}\left\langle X_t^{\otimes n}, f_0^k \right\rangle = \mathbb{E}\left(\left\langle \mu^{\otimes n_t}, f_t^k \right\rangle \exp\left(\frac{1}{2} \int_0^t n_s(n_s - 1) ds\right)\right).$$

Taking limits and using Fatou's lemma, we have

$$\mathbb{E} X(t,x)^{n} \leq \mathbb{E} \left(\left\langle \mu^{\otimes n_{t}}, f_{t} \right\rangle \exp \left(\frac{1}{2} \int_{0}^{t} n_{s}(n_{s}-1) ds \right) \right)$$

$$\leq \exp \left(\frac{1}{2} n(n-1)t \right) \sum_{i=1}^{n} \mathbb{E} \left(\left\langle \mu^{\otimes n_{t}}, f_{t} \right\rangle 1_{\tau_{i-1} \leq t < \tau_{i}} \right).$$

Let i = 3. Then

$$f_t(x_1, \dots, x_{n-2}) \le c \int_{\mathbb{R}^{n-2}} \prod_{i=1}^{n-2} \varphi_{t-\tau_2}(x_i - y_i) \Gamma_2 f_{\tau_2-}(y) dy$$

$$\leq c \int_{\mathbb{R}^{n-2}} \Pi_{i=1}^{n-2} \varphi_{t-\tau_{2}}(x_{i}-y_{i}) \sum_{1 \leq k < \ell} \frac{2}{(n-2)(n-3)}
f_{\tau_{2}-}(y_{1}, \cdots, y_{n-2}, \cdots, y_{n-2}, \cdots, y_{n-3}) dy
\leq c \int_{\mathbb{R}^{n-2}} \Pi_{i=1}^{n-2} \varphi_{t-\tau_{2}}(x_{i}-y_{i}) \sum_{1 \leq k < \ell} \frac{2}{(n-2)(n-3)}
\int_{\mathbb{R}^{n-1}} \Pi_{j=1}^{n-1} \varphi_{\tau_{2}-\tau_{1}}(y_{j}-z_{j}) \varphi_{\tau_{1}}(z_{1}-x) \cdots
\cdots \varphi_{\tau_{1}}(z_{n-2}-x) \varphi_{\tau_{1}}(z_{n-1}-x)^{2} dz.$$

Thus

$$\langle \mu^{\otimes n-2}, f_{t} \rangle \leq c \int_{\mathbb{R}} \varphi_{t-\tau_{2}}(x_{n-2} - y_{n-2}) \mu(dx_{n-2}) \int_{\mathbb{R}} dy_{n-2} \sum_{1 \leq k < \ell} \frac{2}{(n-2)(n-3)}$$

$$\varphi_{\tau_{2}-\tau_{1}}(y_{n-2} - z_{k}) \varphi_{\tau_{2}-\tau_{1}}(y_{n-2} - z_{\ell})$$

$$\int_{\mathbb{R}^{n-1}} \varphi_{\tau_{1}}(z_{1} - x) \cdots \varphi_{\tau_{1}}(z_{n-2} - x) \varphi_{\tau_{1}}(z_{n-1} - x)^{2}$$

$$\leq c \int_{\mathbb{R}} \varphi_{t-\tau_{2}}(x_{n-2} - y_{n-2}) \mu(dx_{n-2}) \int_{\mathbb{R}} dy_{n-2} \frac{1}{\sqrt{\tau_{1}(\tau_{2} - \tau_{1})}} \varphi_{\tau_{2}}(y_{n-2} - x).$$

Therefore

$$\int_{\mathbb{R}} \mathbb{E} \left\langle \mu^{\otimes n_t}, f_t \right\rangle 1_{\tau_2 \le t < \tau_3} dx \le c\mu(\mathbb{R}) \mathbb{E} \frac{1}{\sqrt{\tau_1(\tau_2 - \tau_1)}} < \infty.$$

The other terms can be proved similarly. This finishes the proof of Theorem 1.1.

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